

# **Bayes Days 2000 at LANL**

## **Three-Day Minicourse on Bayesian Analysis in Physics**

Lectures presented by

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Max Planck Institute for Plasma Physics

Sponsored by

Enhanced Surveillance Program, Los Alamos National Laboratory

For more information, look on the web:

<http://public.lanl.gov/kmh/course/BD2000.html>

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## **Deconvolution**

V. Dose, W. von der Linden, R. Fischer  
M. Donath, M. Mayer

1. Apparatus function exact
2. Apparatus function as a result of a measurement

## Deconvolution

measurement

apparatus function

spectral function



$$D(E) = \int_{-\infty}^{\infty} A(E - E') f(E') dE'$$



$$\vec{D} = \mathbf{A} \cdot \vec{f}$$

$$\left. \begin{array}{l} \vec{D} = (D_1, D_2, \dots, D_N)^T \\ \vec{f} = (f_1, f_2, \dots, f_M)^T \end{array} \right\} \rightarrow \dim \mathbf{A} = N \times M$$

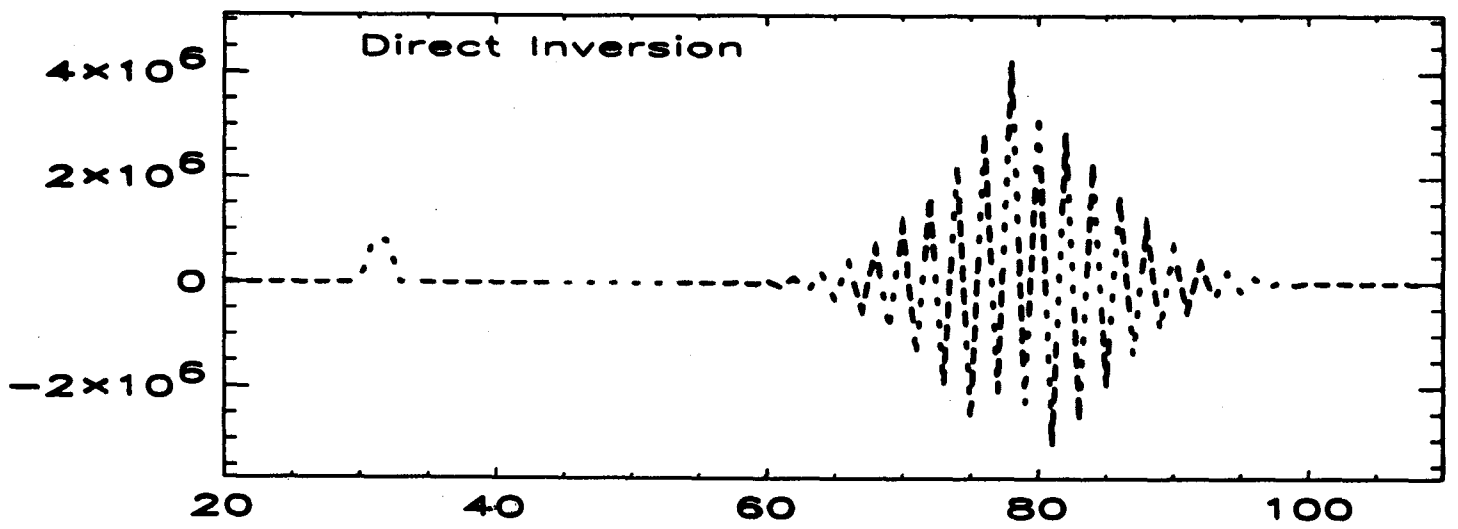
**special case N=M:**

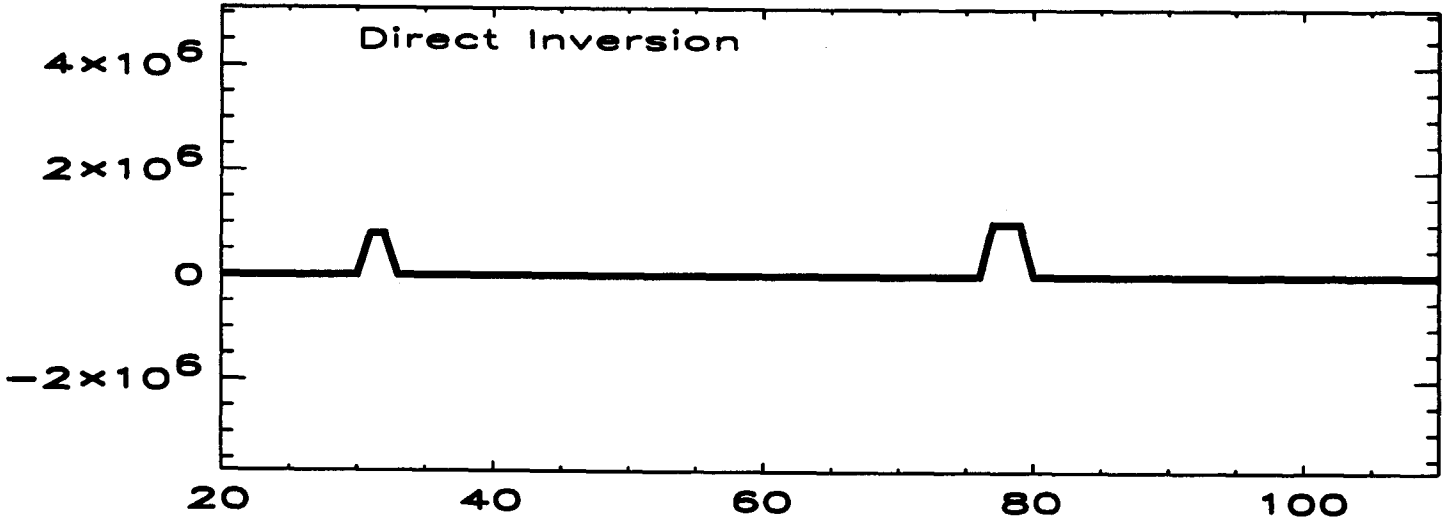
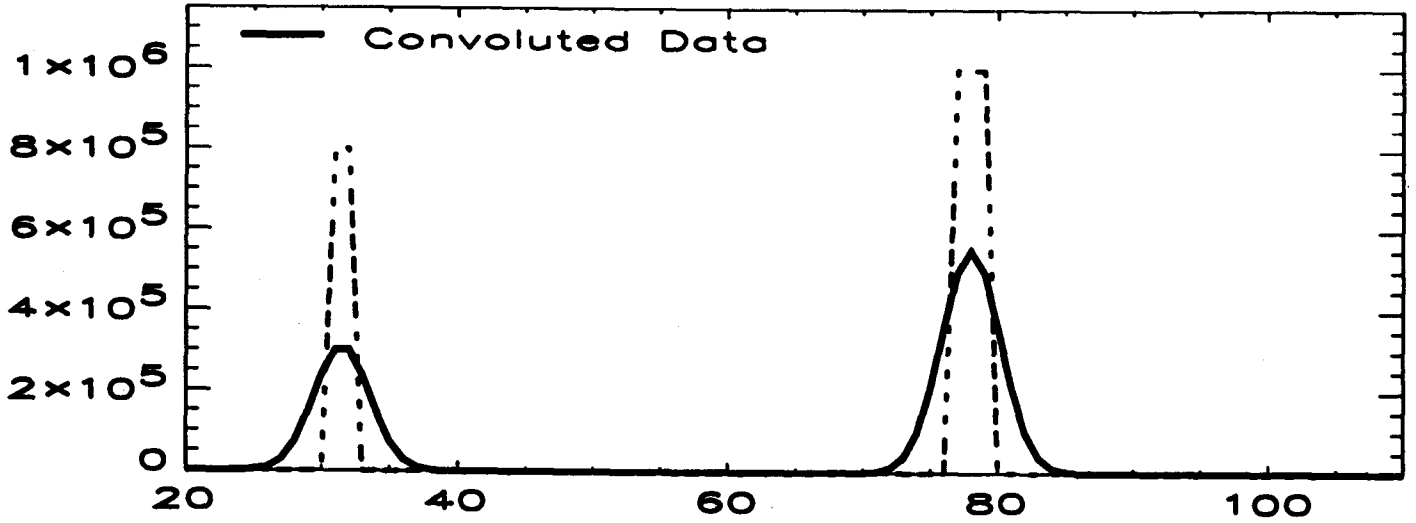
$$\vec{f} = \mathbf{A}^{-1} \cdot \vec{D}$$

**Noise, N=M:**

$$\vec{D} = \mathbf{A} \cdot \vec{f} + \vec{n}_d$$

$$\vec{f} = \mathbf{A}^{-1} \cdot \vec{D} ?$$





## Bayesian solution

$$\langle n_{d_i}^2 \rangle = \sigma_i^2, \quad \langle n_{d_i} \rangle = 0$$

$$p(\vec{D}|\mathbf{A}, \vec{f}, \vec{\sigma}, I) = \left\{ \prod_i \frac{1}{\sigma_i \sqrt{2\pi}} \right\} \exp \left\{ -\frac{1}{2} \sum_i \left[ \frac{D_i - (\mathbf{A}\vec{f})_i}{\sigma_i} \right]^2 \right\}$$

$$p(\vec{f}|\vec{D}, \mathbf{A}, \vec{\sigma}, I) = \frac{p(\vec{f}|I)}{p(\vec{D}|\mathbf{A}, \vec{\sigma}, I)} p(\vec{D}|\mathbf{A}, \vec{f}, \vec{\sigma}, I)$$

$$p(\vec{f}|\alpha, I) = \exp\{\alpha S(\vec{f})\} / Z_S$$

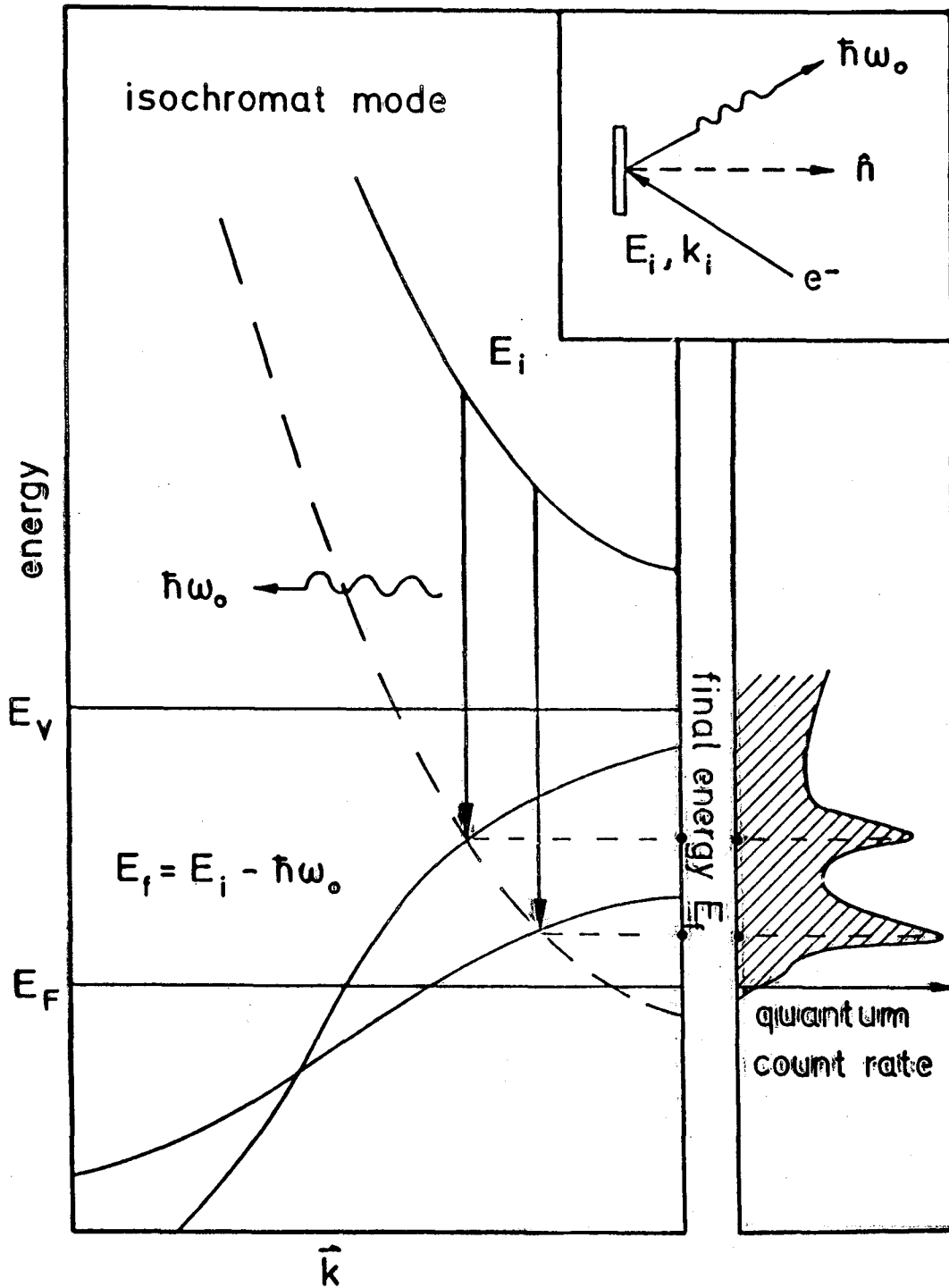
$$S(\vec{f}) = \sum_k \left[ f_k - m_k - f_k \ln\left(\frac{f_k}{m_k}\right) \right]$$

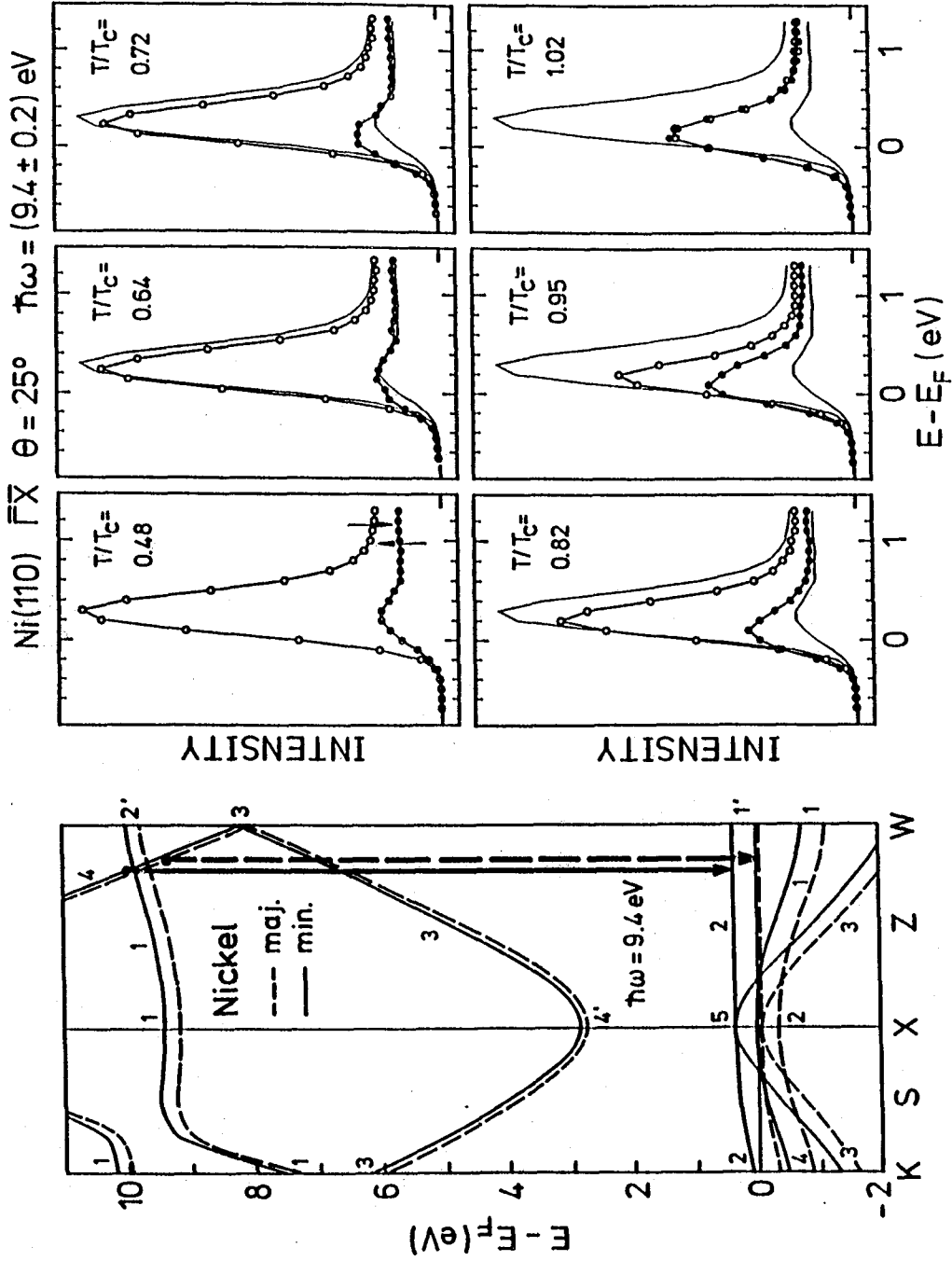
### evidence approximation

$$p(\alpha|\vec{D}, \mathbf{A}, \vec{\sigma}) = p(\alpha|I) \cdot \frac{p(\vec{D}|\mathbf{A}, \vec{\sigma}, \alpha, I)}{p(\vec{D}|\mathbf{A}, \vec{\sigma})}$$

$$\begin{aligned} p(\alpha|\vec{D}, \mathbf{A}, \vec{\sigma}) &= \frac{p(\alpha|I)}{p(\vec{D}|\mathbf{A}, \vec{\sigma})} \int p(\vec{D}, \vec{f}|\mathbf{A}, \vec{\sigma}, \alpha, I) \, d\vec{f} \\ &= \frac{p(\alpha|I)}{p(\vec{D}|\mathbf{A}, \vec{\sigma})} \int p(\vec{f}|\alpha) \cdot p(\vec{D}|\mathbf{A}, \vec{f}, \vec{\sigma}, I) \, d\vec{f} \end{aligned}$$

# inverse photoemission





M. Donath - V.D. Europhys. Lett 9 (1989) 821



$$I^{\uparrow}(E, T, \mu) = j^{\uparrow} \int A^{\uparrow}(E') \{1 - f(E', T, \mu)\} g(E' - E) dE'$$

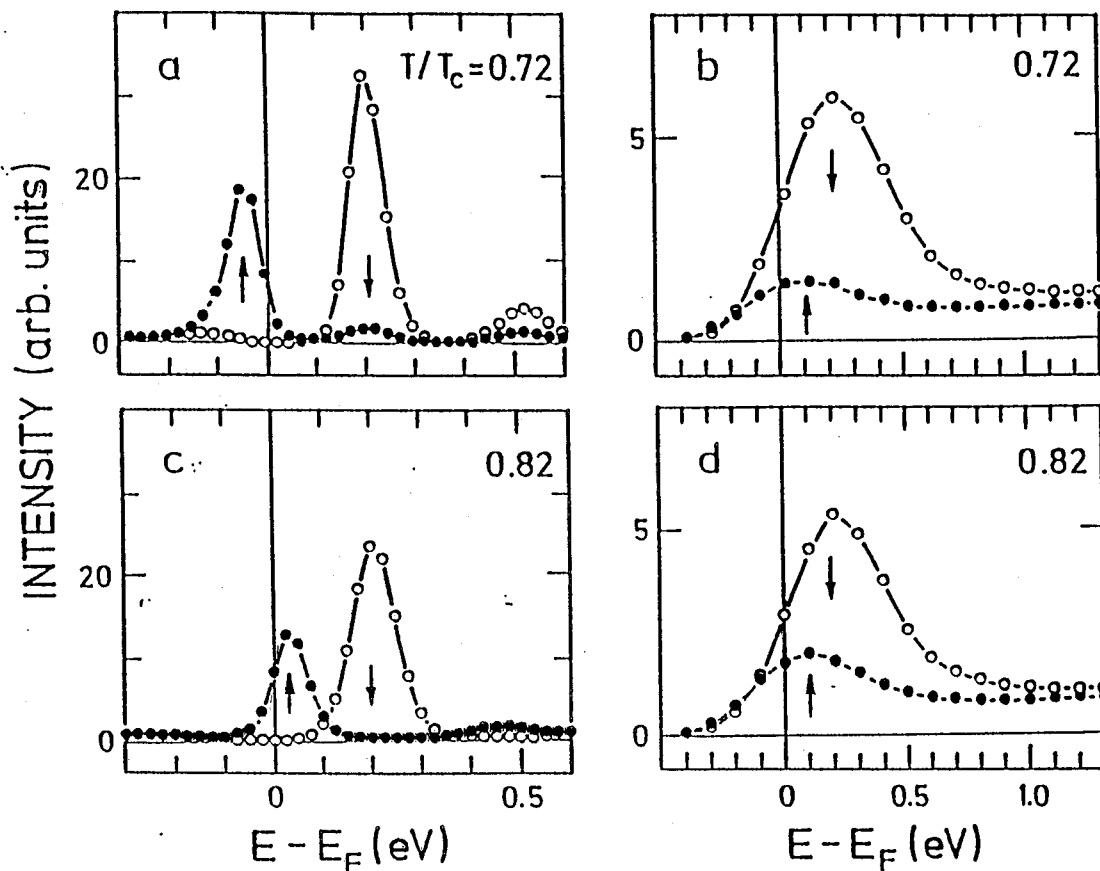
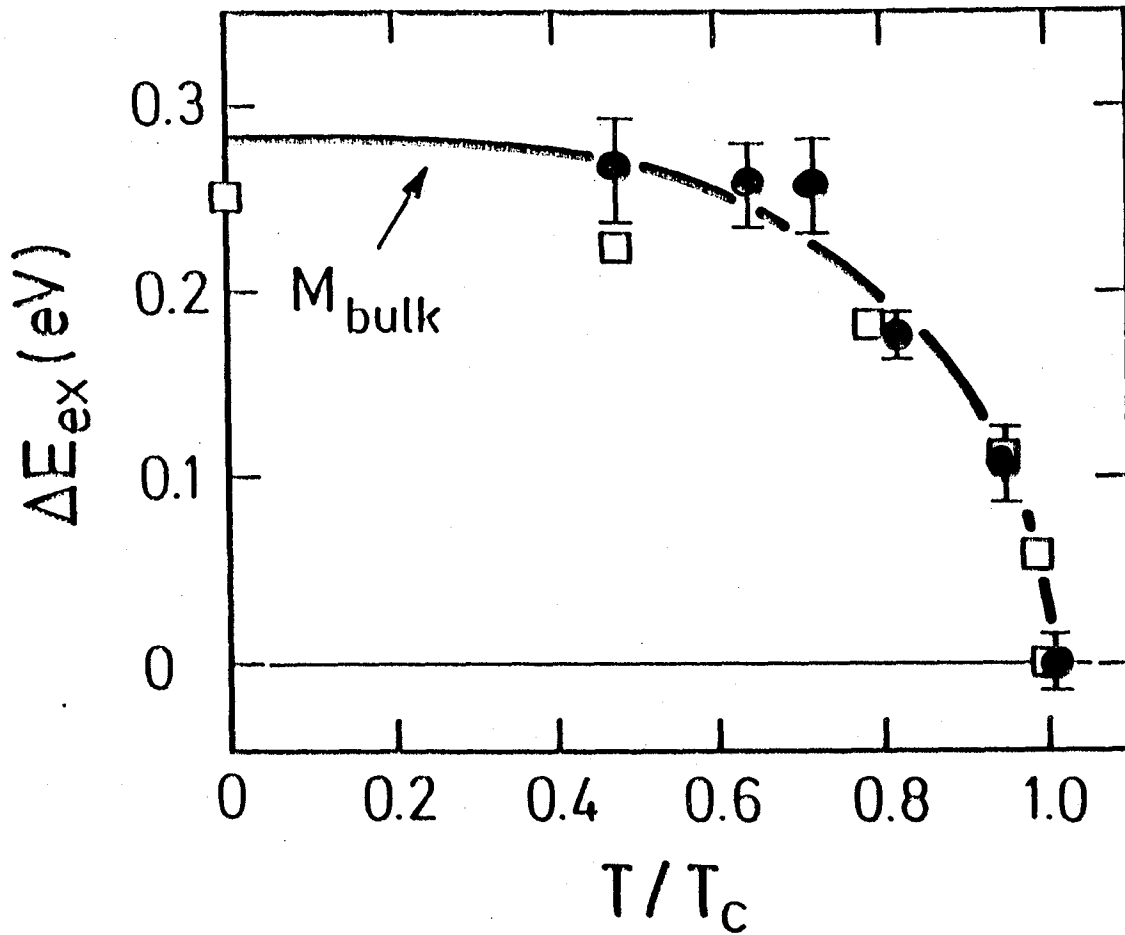


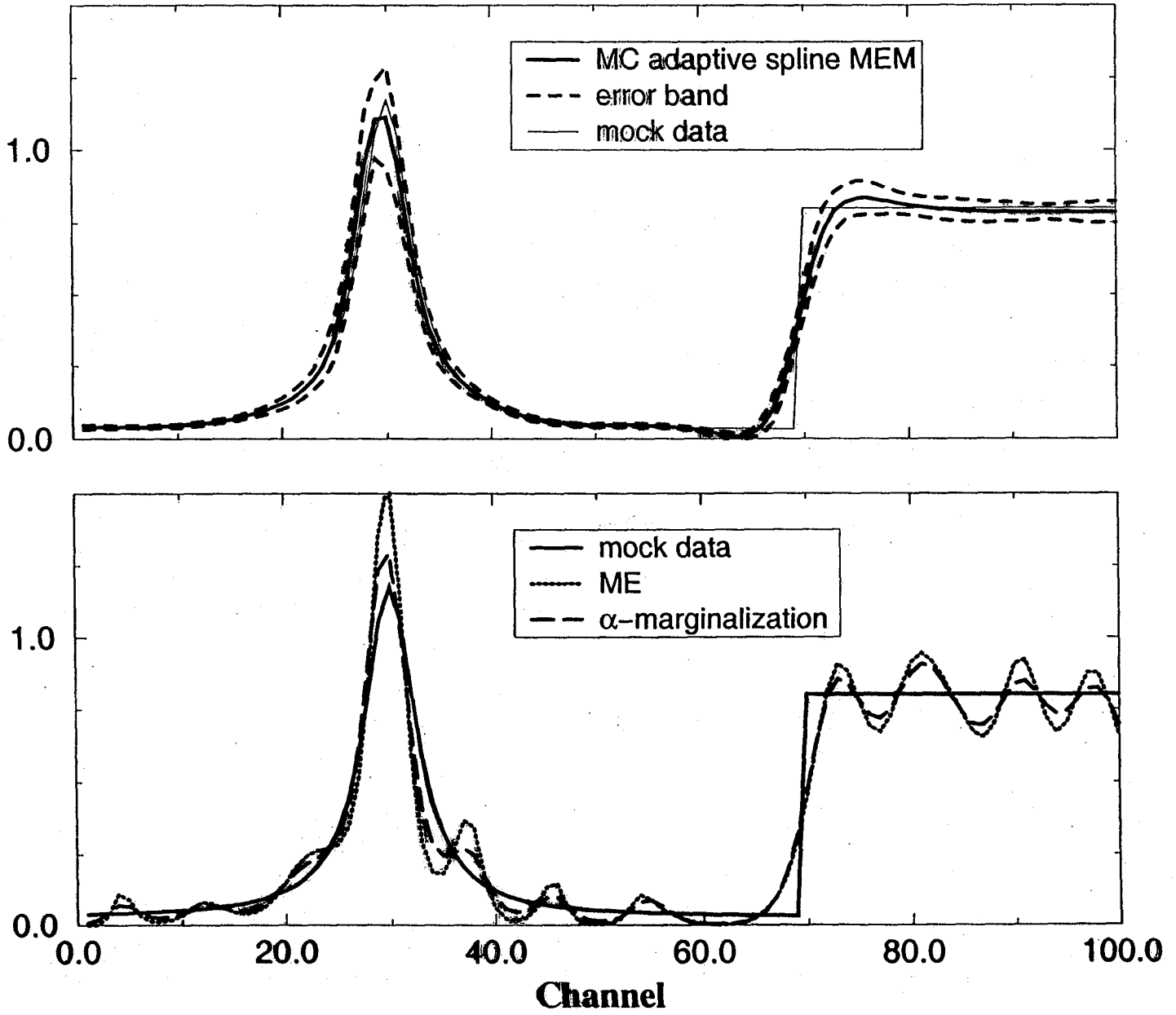
Fig. 2: Spin-dependent quasiparticle spectral density (a,c) and experimental IPE data (b,d) of the  $Z_4 \rightarrow Z_2$ -transition in Ni for two temperatures  $T/T_C = 0.72$  (a,b) and 0.82 (c,d).

v. d. Linden et al. PRL 71 (1993) 899

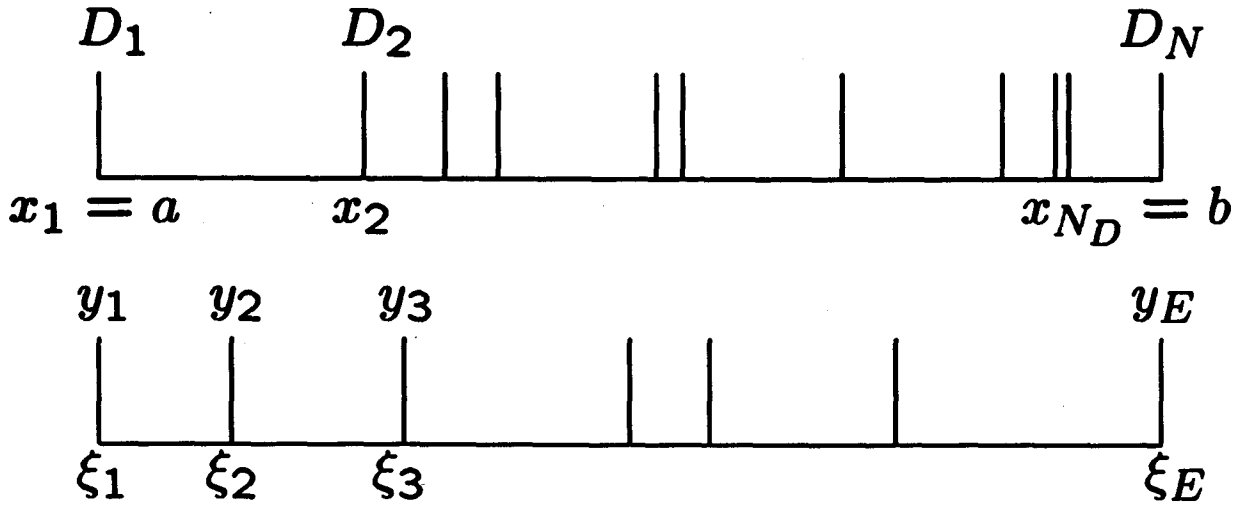


v. d. Linden et al PRL 71 (1993) 899

Borgiel, Nolting, Donath SSC 72 (1989) 825



## Adaptive interpolation model



$$f(x) = f^S(x|E, \vec{\xi}, \vec{y})$$

$$\text{Model : } M = M(E, \vec{\xi})$$

$$p(M|\vec{D}, I) = \frac{p(M|I)}{p(\vec{D}|I)} p(\vec{D}|M, I)$$

$$\begin{aligned} p(\vec{D}|M, I) &= \int p(\vec{D}, \vec{y}|M, I) d\vec{y} \\ &= \int p(\vec{y}|M, I) p(\vec{D}|\vec{y}, M, I) d\vec{y} \end{aligned}$$

$$p(\vec{D}|\vec{y}, M, I) = \left( \prod_i \frac{1}{\sigma_i \sqrt{2\pi}} \right) \exp \left\{ -\frac{1}{2} \sum_i \left( \frac{D_i - f(x_i)}{\sigma_i} \right)^2 \right\}$$

## Priors I

$$p(M|I) = p(\vec{\xi}|E, I) p(E|I)$$

$$p(E|I) = \frac{1}{N}$$

choose  $p(\vec{\xi}|E, I) = \text{flat}$

$$Z = \int_a^b d\xi_2 \int_{\xi_2}^b d\xi_3 \dots \int_{\xi_{E-2}}^b d\xi_{E-1} = \frac{(b-a)^{E-2}}{(E-2)!}$$

$$p(\vec{\xi}|E, I) (\Delta\xi)^{E-2} = \frac{(E-2)!}{(b-a)^{E-2}} (\Delta\xi)^{E-2}$$

$$\frac{p(\vec{\xi}|E+1, I)}{p(\vec{\xi}|E, I)} = \frac{(E-1)\Delta\xi}{b-a}$$

alternatively:

$$p(\vec{\xi}|E, I) = \frac{(E-2)! \prod_{i=2}^E \Theta[\xi_{i-1} + \Delta\xi \leq \xi_{i-1}]}{(b-a - (E-1)\Delta\xi)^{E-2}}$$

## Posterior estimates

$$p(\vec{f}|\vec{D}, E_0, \vec{x}, \vec{\xi}, I) = \int p(\vec{f}, \vec{y}|\vec{D}, E_0, \vec{x}, \vec{\xi}, I) d^{E_y}$$

$$= \int p(\vec{f}|\vec{D}, E_0, \vec{y}, \vec{x}, \vec{\xi}, I) p(\vec{y}|\vec{D}, E_0, \vec{\xi}, I) d^{E_y}$$

$$p(\vec{f}|\vec{D}, E_0, \vec{y}, \vec{x}, \vec{\xi}, I) = \delta(\vec{f} - \mathbf{S}(x, \vec{\xi})\vec{y})$$

Bayes theorem:

$$p(\vec{y}|\vec{D}, E_0, \vec{x}, \vec{\xi}, I) = \frac{p(\vec{y}|E_0, \vec{\xi}, I)}{p(\vec{D}|I)} p(\vec{D}|\vec{y}, E_0, \vec{x}, \vec{\xi}, I)$$

$$\langle g(\vec{f}) \rangle = \int g(\vec{f}) p(\vec{f}|\vec{D}, E_0, \vec{x}, \vec{\xi}, I) d^{E_0} f$$

in particular

$$g(f) = f \quad g(f) = f^2$$

## Priors II

$$p(\vec{y}|M, I) = \exp\{-\Phi(f(\vec{y}))\} / Z(M)$$

for a general quadratic log prior

$$p(f) = \exp\left\{-\frac{\lambda}{2} \vec{f}^T \mathbf{A} \vec{f}\right\} / Z(\lambda, f)$$

consistent with spline

$$\Phi = \int_a^b |f''|^2 dx$$

$$f^S = \mathbf{S} \vec{y}$$

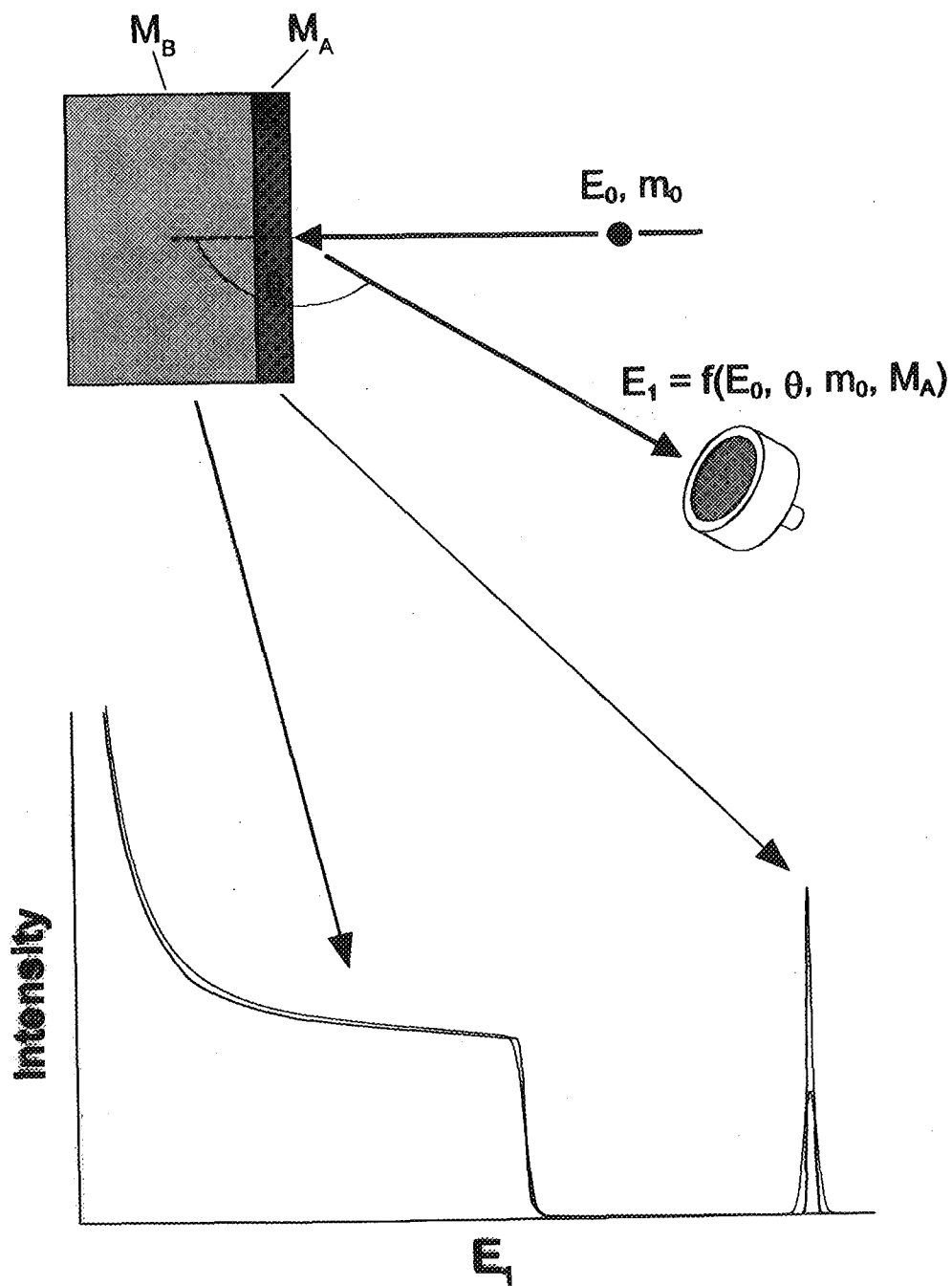
$$p(\vec{y}|M, \lambda, I) = \left(\frac{\lambda}{2\pi}\right)^{E/2} \sqrt{\det \mathbf{S}^T \mathbf{A} \mathbf{S}} \exp\left\{-\frac{\lambda}{2} \vec{y}^T \mathbf{S}^T \mathbf{A} \mathbf{S} \vec{y}\right\}$$

$$p(\vec{y}|M, I) = \int p(\vec{y}|M, \lambda, I) p(\lambda|I) d\lambda$$

Jeffrey's prior

$$p(\lambda|I) = \frac{d\lambda}{\lambda} \rightarrow p(\lambda|I) = \frac{a^\gamma}{\Gamma(\gamma)} \lambda^{\gamma-1} e^{-a\lambda}$$

( $a \rightarrow 0, \gamma \rightarrow 1$ )





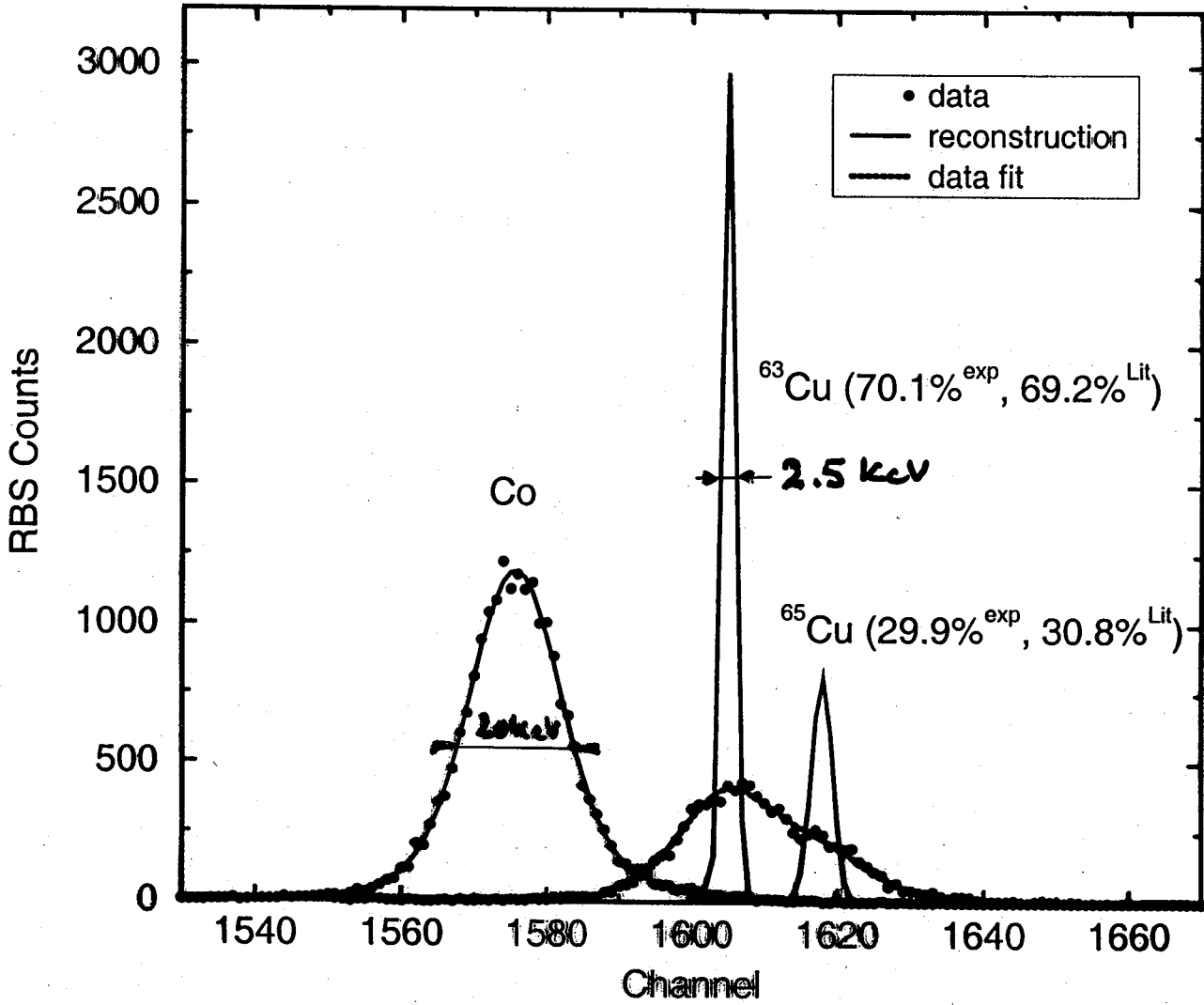
## Broadening mechanismus

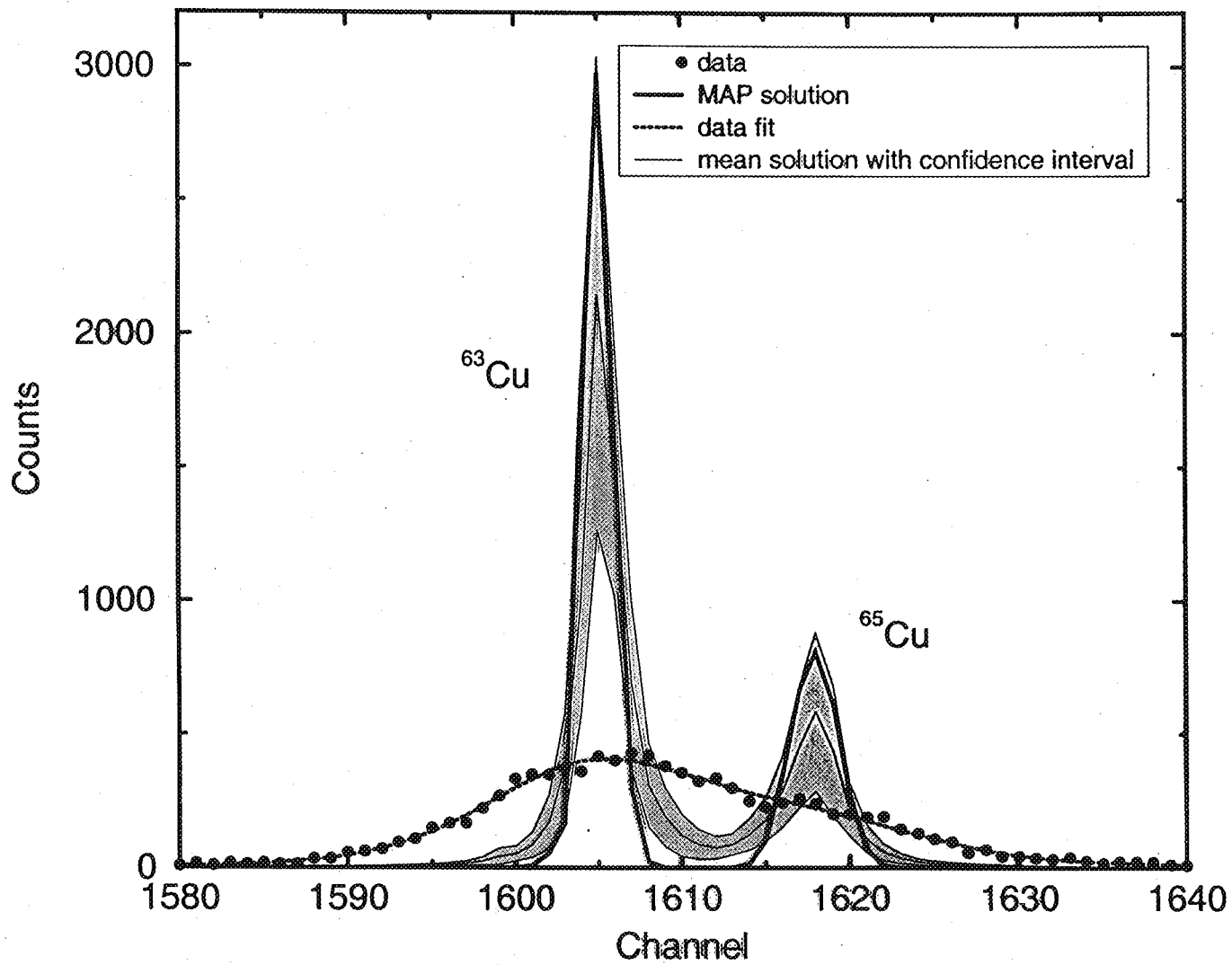
1. incident beam energy  
at  $E_0=2.6$  MeV  $\approx 13$  keV
2. detector resolution at  
 $E_1 \approx 2$  MeV  $\approx 15$  keV
3. electronic noise  $\approx 5$  keV
4. detector solid angle, beam spot size,  
finite film thickness  $\approx 3$  keV

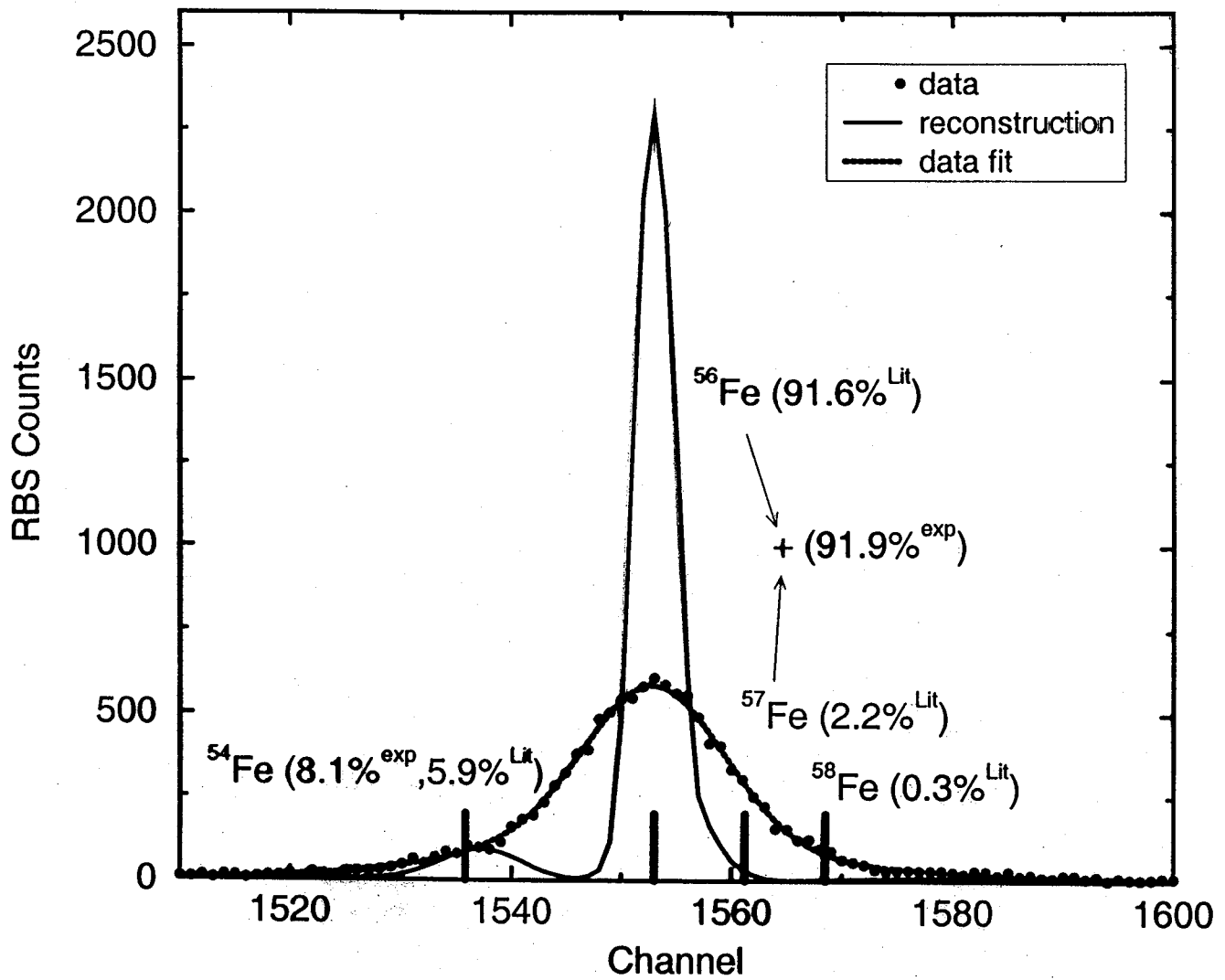
**overall resolution 20.6 keV**

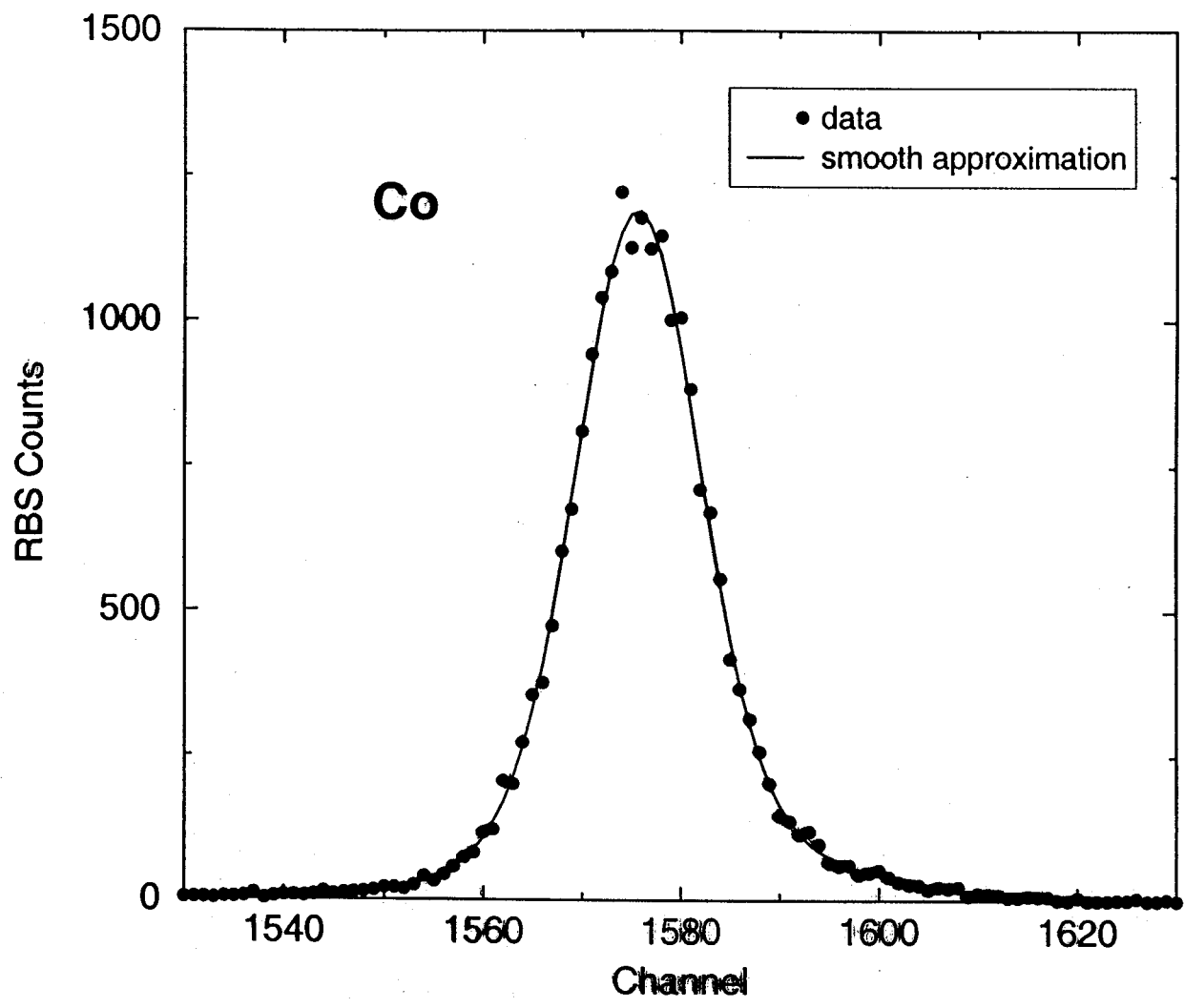
$$D(E) = \int f(E') A(E - E') dE'$$

MAP - Solution









$$\vec{D} = \mathbf{A}\vec{f} + \vec{n}_d$$

now: apparatus function  $\mathbf{A}$  also noise corrupted:  $\tilde{\mathbf{A}}$

$$p(\vec{D}|\vec{f}, \mathbf{A}, \vec{\sigma}, I) = \exp \left\{ -\frac{1}{2} \sum_i \left( \frac{D_i - \sum_k a_{ik} f_k}{\sigma_i} \right)^2 \right\} / Z_L$$

$$p(\vec{D}|\vec{f}, \tilde{\mathbf{A}}, \vec{\sigma}, \delta, I) = \int da_{ik} p(\mathbf{A}|\tilde{\mathbf{A}}, \delta, I) p(\vec{D}|\mathbf{A}, \vec{f}, \vec{\sigma}, I)$$

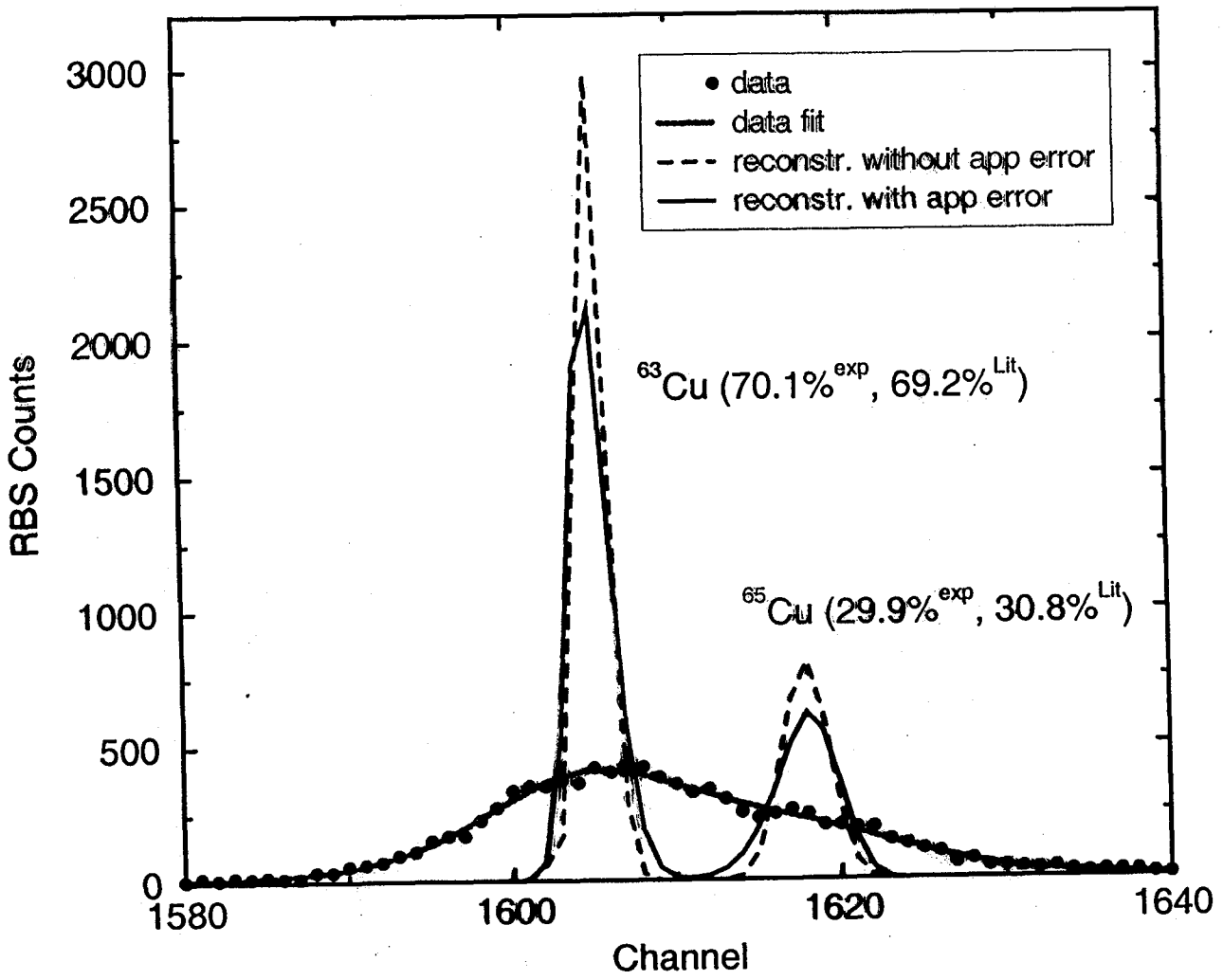
$$p(\mathbf{A}|\tilde{\mathbf{A}}, \delta, I) = \exp \left\{ -\frac{1}{2} \sum_{i,k} \left( \frac{a_{ik} - \tilde{a}_{ik}}{\delta_{ik}} \right)^2 \right\} / Z_P$$

$$p(\vec{D}|\vec{f}, \tilde{\mathbf{A}}, \delta, \vec{\sigma}, I) = \exp \left\{ -\frac{1}{2} \sum_i \frac{[D_i - (\tilde{\mathbf{A}}\vec{f})_i]^2}{\sigma_i^2 + \sum_k f_k^2 \delta_{ik}^2} \right\} / Z$$

$$\Sigma_i^2 = \underbrace{\sigma_i^2}_{\text{measurement of data D}} + \underbrace{\sum_k f_k^2 \delta_{ik}^2}_{\text{measurement of apparatus function } \tilde{\mathbf{A}}}$$

measurement of  
data D

measurement of  
apparatus function  $\tilde{\mathbf{A}}$



## Convolution theorem

$$h(E) = \int f(E') A(E - E') dE'$$

$$M^n(h) = \int E^n h(E) dE = \int E^n dE \int f(E') A(E - E') dE'$$

$$\text{Let } E = E' + y \rightarrow E^n = \sum_{i=0}^n \binom{n}{i} y^i (E')^{n-i}$$

$$M^n(h) = \sum_{i=0}^n \binom{n}{i} M^i(A) M^{n-i}(f)$$

normalized functions, centred moments:

$$\text{var}(h) = \text{var}(A) + \text{var}(f)$$

let width of image  $f \approx \alpha \cdot$  (width of measurement  $h$ ),  $\alpha < 1$ :

$$\text{var}(h) = \text{var}(A) + \alpha^2 \text{var}(h)$$

$$\frac{\text{width}(A)}{\text{width}(h)} = \sqrt{1 - \alpha^2} = \begin{cases} 0.986, \alpha = \frac{1}{6} \\ 0.992, \alpha = \frac{1}{8} \end{cases}$$



